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Term End Examination 2024-2025
Programme – M.Tech.(CSE)-AIML-2023
Course Name – Pattern Recognition
Course Code - PEC-MCSM301A
(Semester III)

Full Marks: 60

Time: 2:30 Hours

[The figure in the margin indicates full marks. Candidates are required to give their answers in their own words as far as practicable.]

Group-A

(Multiple Choice Type Question)

1 x 15=15

- Choose the correct alternative from the following :
- (i) Choose the correct option, in a typical pattern recognition application, the raw data is processed and converted into a form that is amenable for a machine to use.
 - a) = TRUE()

b) =FALSE()

c) Can be true or false

- d) Can not say
- (ii) Recognize the type of process that has a constant mean and variance over time.
 - a) Non-stationary process

b) Random process

c) Stationary process

- d) Independent process
- (iii) Identify the key assumption in the Bayesian classifier for minimizing classification error.
 - a) Class conditional densities are normally distributed
- b) All features are discrete
- c) The prior probabilities are unknown
- d) The data is independent and identically distributed (i.i.d.)
- (iv) Distinguish between discrete features and continuous features in Bayesian classifiers.
 - a) Discrete features require parametric modeling, continuous features require nonparametric
 - c) Discrete features use likelihood functions, continuous features use probability mass
- (v) Define Maximum-Likelihood Estimation (MLE).
 - a) A method to maximize the prior probability of a parameter
 - c) A method to minimize the variance of the dataset

- b)
 Discrete features are represented by probability density functions
- d) Discrete features are modeled with probability mass functions, continuous features with probability density functions
- b) A method to estimate the parameters that maximize the likelihood of the observed data
- d) A method to estimate Bayesian posterior probabilities
- (vi) Discuss the importance of the E-step in the EM algorithm.



a) It estimates the parameters of the model b) It updates the model using observed data c) It computes the expected value of the d) It refines the clustering process latent variables given current parameters (vii) Identify the components of a discrete HMM. a) States, observations, transition probabilities b) States, features, classification labels c) Observations, parameters, model accuracy d) Inputs, outputs, training data (viii) Illustrate how the Forward Algorithm works in HMMs. a) It calculates the most likely path of hidden b) It computes the probabilities of sequences of observed events states c) It finds the optimal transition probabilities d) It initializes the model parameters (ix) Compare supervised learning to unsupervised learning in classification. a) Supervised learning requires labeled data; b) Both require labeled data unsupervised does not d) Unsupervised learning is less effective c) Both use the same algorithms (x) Identify how SVMs deal with outliers in the dataset. a) SVMs ignore outliers b) SVMs can be adjusted to allow for soft margins to accommodate outliers c) SVMs become ineffective with outliers d) SVMs only work with clean datasets (xi) Define autocorrelation in the context of random processes. a) The correlation between two different b) The correlation of a signal with a delayed processes version of itself c) The variance of a random process d) The mean of a random process (xii) Identify the difference between joint and conditional probability. a) Joint probability considers two events b) Joint probability is the same as conditional occurring simultaneously; conditional probability considers one given the other c) Conditional probability is always greater d) Both probabilities cannot be calculated than joint probability together (xiii) Compare the role of prior and likelihood in Bayesian classifiers. a) Prior controls data distribution, likelihood b) Prior affects decision surfaces, likelihood controls classification defines the boundary c) Prior updates class membership, likelihood d) Prior maximizes accuracy, likelihood assigns class probability minimizes error rates (xiv) Explain the purpose of Maximum-Likelihood Estimation (MLE) in parameter estimation. a) To estimate the parameters that maximize b) To minimize the variance of the parameters the data likelihood c) To reduce the dimensionality of data d) To increase the mean of the data (xv) Analyze the advantage of Bayesian estimation over Maximum-Likelihood Estimation in situations with limited data. a) Bayesian estimation incorporates prior b) Bayesian estimation performs better with distributions and handles uncertainty larger datasets c) Bayesian estimation always provides a d) Bayesian estimation is less computationally unique solution complex

Group-B

(Short Answer Type Questions)

3 x 5=15

2. Classify the types of training methods used for deep learning neural networks and their relevance to model performance.

3. Write some common challenges in pattern recognition.

4. Illustrate the working of a normal density function in classification with an example.

(3)

5.	Illustrate the concept of Bayesian estimation and how it differs from maximum-likelihood estimation.	(3)	
6.	Discuss the significance of non-metric methods in pattern classification and provide an example.	(3)	
	OR Classify the types of clustering methods and their suitability for different data types in unsupervised learning.	(3)	
Group-C			
		5 x 6=30	
9. 10	distributions. Summarize how parameter estimation methods contribute to the development of unsupervised learning algorithms. Analyze the role of backpropagation in training neural networks. Explain how K-means clustering algorithm works and its applications in data analysis. OR	(5) (5) (5) (5) (5)	
	Explain hierarchical clustering and compare it with K-means clustering.	(5)	
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