



## BRAINWARE UNIVERSITY

Term End Examination 2021 - 22
Programme – Diploma in Computer Science & Engineering
Course Name – Artificial Intelligence
Course Code - DCSE602
( Semester VI )

Fime allotted : 1 Hrs.25 Min.	Full Marks : 79
[The figure in the n	nargin indicates full marks.]
•	Group-A
(Multiple Cl	noice Type Question) 1 x 70=70
Choose the correct alternative from the following:	
(1) What is Artificial intelligence?	
a) Putting your intelligence into Computer	<ul> <li>b) Programming with your own intelligence</li> </ul>
c) Making a Machine intelligent	d) Playing a Game
(2) Which instruments are used for perceiving and	acting upon the environment?
a) Perceiver	b) Sensors and Actuators
c) Sensors	d) None of the mentioned
(3) What is the rule of simple reflex agent	
a) Simple-action rule	b) Condition-action rule
c) Both a & b	d) None of the mentioned
(4) Which is used to improve the agents performan	nce?
(a) Perceiving	b) Learning
c) Observing	d) None of the mentioned
(5) Where the next state and the action of an agent current state?	of the environment is fully obtained based on the
a) Deterministic environment	b) Episodic environment
c) Non-deterministic environment	d) None of these
(6) When agents select actions on the basis of pref	erence for each state, called
a) Utility based agents	b) Model based reflex agents
c) Goal based agents	d) None of these
(7) Driving is belongs to which category of enviro	nment?
a) Discrete	b) Continuous
c) Static	d) Dynamic
(8) Where one real and other artificial agents are s	imultaneously tested on the basis of equal ground?
a) Utility based Test environment	b) Turing Test environment
c) Model based Test environment	d) None of these
(9) The Set of actions for a problem in a state space	e is formulated by a

a) Intermediate state	b) Initial state	Bratoware University
<ul> <li>c) Successor function, which takes current action an d returns next immediate state</li> </ul>	d) None of these	Barusat, Kalkata -700125
(10) To represent state space diagram of 8-puzzle problem	m in AI, possible mo	ves are:
a) Left and Right	b) Right and Up	
c) Up and Down	d) Left, right, up	and down
(11) Adversarial search uses which type of agent?		
a) Co-operative multi-agen	b) Co-operative 1	nulti-agen
c) Co-operative single-agent	d) Competitive s	ingle-agent
(12) Rubik's Cube is		
<ul> <li>a) Single agent path finding problems</li> </ul>	b) Multi agent pa	nth finding problems
c) Both of these	d) None of these	
(13) The summation of initial state and goal state make a	a	
a) Problem Space	b) Problem insta	nce
c) Problem Space Graph	d) None of these	
(14) Which agent enables the deliberation about the con-	nputational entities ar	nd actions?
a) Hybrid	b) Reflective	
c) Relational	d) None of the n	nentioned
(15) Web Crawler is a kind of		
<ul> <li>a) Intelligent goal-based agent</li> </ul>	b) Problem-solv	ing agent
c) Simple reflex agent	d) Model based	agent
(16) Forward reasoning is		
a) Data driven	<ul><li>b) Goal driven</li></ul>	
c) Knowledge driven	d) Resolution dr	riven
(17) Which search algorithm imposes a fixed depth lim	it on nodes?	
a) Depth-limited search	b) Depth-first se	earch
c) Iterative deepening search	d) Bidirectional	search
(18) Which search implements stack operation for search	ching the states?	
a) Depth-first search	b) Breadth-first	search
c) Bidirectional search	d) None of the	mentioned
(19) is an algorithm, a loop that con alue that is uphill	tinually moves in the	direction of increasing v
a) Up-Hill Search	b) Hill-Climbin	g
c) None of these	d) Reverse-Dov	vn- Hill search
(20) Best-First search can be implemented using	data structure	
a) Queue	b) Stack	
c) Priority Queue	d) Circular Que	eue
(21) Which search is implemented with an empty first-	in- first-out queue?	
a) Depth-first search	b) Breadth-firs	t search
c) Bidirectional search	d) None of the	mentioned
(22) Adversarial search problems uses		
a) Competitive Environment	b) Cooperative	Environment
c) Neither a nor b	d) All of these	2 a controlle
(23) DFS is efficient and BFS is		
a) Space, Time	b) Time, Space	
c) Time, Time	d) Space, Space	
(24) To which depth does the alpha-beta pruning can b		
	w albumetti	

a) 10	0) 13
e) 5	d) Any depth Brainware University
(25) Which search is similar to minimax search?	Baraset, Kelkate -700125
a) Depth-first search	b) Breadth-first search
c) Hill climbing	d) None of these
(26) Value of utility function for representing state sp	pace diagram for tic-tac-toe are
a) 1,2,0	b) 1,-1,0
c) 1,1,1	d) -1,-1,0
(27) BFS uses which data structure?	
a) Stack	b) Queue
c) Priority queue	d) Linked list
(28) The adjective "first-order" distinguishes first-order redicates having predicates or functions as argur fiers or function quantifiers are permitted.	der logic from in which there are p ments, or in which one or both of predicate quanti
a) Representational Verification	b) Representational Adequacy
c) Higher Order Logic	d) Inferential Efficiency
(29) Mathematical representation of space requireme	ent for storing nodes in Breadth-First Search
•	
(a) Exponential	b) Logarithmic
c) Geometric progression	d) None of these
(30) A search technique where searches is done on the e and goal state respectively till both meet to ide	ne basis of forward and backward from initial statentify a common state
a) Bidirectional search	b) Breadth- first search
c) Depth- first search	d) None of these
(31) The deficiency in uniform Cost Search	and the state of t
a) It has no information on goal location	b) It does not explore options in every direction.
c) It is not optimal	d) None of these
(32) A search technique that combines the strengths of	of uniform-cost search and greedy search
a) A* Tree Search	b) A* graph Search
c) Hill climbing search	d) None of these
(33) Space complexity for Uniform Cost search	- Particular antico
a) (b: no. of node, d: depth)	b) (b: no. of node, d: depth)
c) (b: no. of node, d: depth)	d) (b: no. of node, d: depth)
(34) A set of objects whose state must satisfy a numb problem.	per of constraints or limitation belong to
a) Constraints Satisfaction Problems	b) Uninformed Search Problems
c) Local Search Problems	d) All of the mentioned
(35) Value of alpha and beta in the alpha-beta pruning	9
a) Alpha = max	b) Beta = min
c) Beta = max	d) Both Alpha = max & Beta = min
(36) Flexible Constraint Satisfaction Problems relax of	
a) Constraints	b) Current State
c) Initial State	d) Goal State
(37) Fuzzy logic is a form of	
a) Two-valued logic	b) Crisp set logic
c) Many-valued logic	d) Binary set logic
(38) Which search is equal to minimax search but elir	

l decision?	
a) Depth-first search	b) Breadth-first search
c) Alpha-beta pruning	d) None of the mentioned
(39) "John is very intelligent". This statement can be	d) None of the mentioned be completely expressed in b) Fuzzy logic d) Propositional logic
a) FOPL	b) Fuzzy logic d) Propositional logic
c) Default logic	d) Propositional logic
(40) Backward reasoning is	•
a) Data driven	b) Goal driven
c) Knowledge driven	d) Resolution driven
nsequence of another formula.	rely syntactic basis, that one formula is a logical co
a) Deductive Systems	b) Inductive Systems
c) Reasoning with Knowledge	d) Search Based Systems
(42) How many logical connectives are there in ar	tificial intelligence?
a) 2	b) 3
c) 4	d) 5
(43) Which is also called single inference rule?	
a) Reference	b) Resolution
c) Reform	d) None of these
(44) The room temperature is hot. Here the hot (us by	se of linguistic variable is used) can be represented
a) Fuzzy set	b) Crisp set
c) Both fuzzy and crisp set	d) None of these
(45) Semantic Networks is	
a) A way of representing knowledge	b) Data structure
c) Data type	d) None of these
(46) Frames is	
a) A way of representing knowledge	b) Data structure
c) Data type	d) None of these
(47) Defuzzification is process of conversion of	
a) Fuzzy set to crisp set	b) Crisp to fuzzy set
c) Both a. and b.	d) None of these
(48) Forward chaining is a	
a) Type of knowledgebase	b) Type of planning
c) Type of learning	d) Method of reasoning
(49) Knowledge based inductive learning(KBIL)	
a) Inductive learning	b) Deductive learning
c) Supervised learning	d) Unsupervised learning
(50) Explanation-Based Learning(EBL) is examp	
a) Inductive learning	b) Deductive learning
c) Supervised learning	d) Unsupervised learning
(51) Clustering is a classic example of	d) Olisupervised learning
	1) P
a) Semi-supervised learning models.	b) Reinforcement learning models
c) supervised learning models.	d) unsupervised learning models.
(52) Regression is classic example of	
a) Semi-supervised learning models.	b) Reinforcement learning models
c) supervised learning models.	d) unsupervised learning models.

(53) Association is classic example of			
<ul> <li>a) Semi-supervised learning models.</li> </ul>	b) Reinforcement learning models		
c) supervised learning models.	d) unsupervised learning models.  b) First-Order Python Logic		
(54) FOPL stands for	arathmere of the Tour 25		
a) First-Order Prolog Logic	b) First-Order Fytholi Logic		
c) First-Order Predicate Loop	d) First-Order Predicate Logic		
(55)transforms the fuzzy set obtained by the	e inference engine into a crisp value.		
a) defuzzification Module	b) knowledge base		
c) both of these	d) None of these		
(56) IF-THEN rules provided by experts is stored in	n .		
a) defuzzification Module	b) knowledge base		
c) Expert system	d) None of these		
(57) A teacher usefor addressing dec	larative knowledge.		
a) Evaluating mathematical expressions	b) How to write definitions to vocabulary words		
c) Both of these	d) None of these		
(58) NLP (with respect of AI) stands for			
a) Natural Linear Processing	b) Natural Language Processing		
c) Natural Linear Programming	d) Natural Language Programming		
(59) How many components does Natural Language	ge Processing (NLP) has?		
a) 2	b) 3		
c) 4	d) 5		
(60) Text planning is involved in			
a) Natural Language Understanding	b) Natural Language Generation		
c) Both a and b	d) None of these		
(61) A Horn clause is a clause with	<u>.</u>		
a) at most one negative literal	b) at most two negative literal		
c) at most one positive literal	d) at most two positive literal		
(62) Pattern recognition systems such as face reco			
a) Expert Systems	b) Natural Language Processing		
c) Neural Networks	d) Robotics		
(63) Flight-tracking system is application of			
a) Expert Systems	b) Natural Language Processing		
c) Neural Networks	d) Robotics		
(64) Treating the word "board" as noun or verb is			
a) Lexical ambiguity	,		
c) Referential ambiguity	b) Syntax Level ambiguity		
	d) None of these		
a) Context consisting arranged as Single	symbol on the left-hand side of the rewrite rules		
a) Context sensitive grammar	b) Context free grammar		
c) Pragmatic analysis	d) Semantic Analysis		
(66) Expert system without knowledge base called	ed		
a) Shells	b) Tools		
c) user interface	d) none of these		
(67) The process of completing a specific task by mand is referred as	y the brain which incrementally orders actions on de		
a) Planning problem	h) Partial order planning		
c) Total order planning	b) Partial order planning		
(68) Which of the following option is true?	d) Both Planning problem & Partial order planning		

a)	If	the	Sun	is a	planet,	elephants	will fly
	-	_					

b) 3 + 2 = 8 if 5 - 2 = 7

c) 1 > 3 and 3 is a positive integer

d) -2 > 3 or 3 is a negative integer

(69) What is the value of x after this statement, assuming initial value of x is 5? 'If x equals to one the n x=x+2 else x=0'.

a) 1

b) 3

c) 0

d) 2

Brainware University -7

(70) Let P: I am in Delhi., Q: Delhi is clean.; then q ^ p(q and p) is:

a) Delhi is clean and I am in Delhi

b) Delhi is not clean or I am in Delhi

c) I am in Delhi and Delhi is not clean

d) Delhi is clean but I am in Mumbai