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BRAINWARE UNIVERSITY

Term End Examination 2021 - 22
Programme – Bachelor of Computer Applications
Course Name – Artificial Intelligence
Course Code - BCAD502B
(Semester V)

Time: 1 Hr.15 Min.

Full Marks: 60

[The figure in the margin indicates full marks.]

Group-A

(Multiple Choice Type Question)

1 x 60=60

Choose the correct alternative from the following:

- (1) Which element in agent is used for selecting external actions?
 - a) a. Perceive

b) b. Performance

c) c. Learning

- d) d. Actuator
- (2) External actions of the agent are selected by
 - a) a. Perceive

b) b. Performance

c) c. Learning

- d) d. Actuator
- (3) The action of the Simple reflex agent completely depends upon
 - a) a. Perception history

b) b. Current perception

c) c. Learning theory

- d) d. Utility functions
- (4) Agents behaviour can be best described by
 - a) a. Perception sequence

b) b. Agent function

c) c. Sensors and Actuators

- d) d. Environment in which agent is performing
- (5) In which agent, the problem generator is present?
 - a) a. Learning agent

b) b. Observing agent

c) c. Reflex agent

d) d. None of these

- (6) An 'agent' is anything that,
 - a) a. Perceives its environment through sensors and acting upon that environment through ac tuators
- b) b. Takes input from the surroundings and use s its intelligence and performs the desired op erations
- c) c. A embedded program controlling line foll owing robot
- d) d. All of these
- (7) A heuristic is a way of trying
 - a) a. To discover something or an idea embedde d in a program
- b) b. To search and measure how far a node in a search tree seems to be from a goal

| e) c. To compare two nodes in a search tree to see if one is better than the other | d) d. All of these | |
|---|---|--|
| (8) Which search method takes less memory? | | |
| a) a. Depth-First Search | b) b. Breadth-First search | |
| c) a. Both Depth First Search and Breadth First Search | d) b. Linear Search | |
| (9) Which is true regarding BFS? | | |
| a) a. BFS will get trapped exploring a single pa th | b) b. The entire tree so far been generated must be stored in RFS | |
| c) c. BFS is not guaranteed to find a solution, if exists | d) d. BFS is nothing but Binom, E' | |
| (10) What is the term used for describing the judgen solving? | nental or common-sense part of problem | |
| a) a. Heuristic | | |
| c) c. Value based | b) b. Critical | |
| (11) What is a heuristic function? | d) d. Analytical | |
| a) a. A function to solve mathematical problem | | |
| | b) b. A function which takes parameters of type | |
| c. A function whose return to | string and returns an integer value | |
| c) c. A function whose return type is nothing (12) n which touring problem, each city must be visit shortest tour. | d) d. A function that maps from problem state d escriptions to measures of desirability. | |
| shortest tour. | ned exactly once? The aim is to find the | |
| a) a. Finding shortest path between a source an d a destination | b) b. Travelling Salesman problem | |
| c. Map coloring problem | d) d. Denth first sanrah | |
| (13) A production rule consists of | d) d. Depth first search traversal on a given ma p represented as a graph | |
| a) a. A set of Rule | b) b | |
| c) c. Set of Rule & sequence of steps | b) b. A sequence of steps | |
| (14) A problem solving approach works well for | d) d. Arbitrary representation to problem | |
| a) a. 8-Puzzle problem | b) b 0 | |
| c) c. Finding a optimal path from a given source to a destination | b) b. 8-queen problem d) d. Mars Hover (Robot Navigation) | |
| (15) Which is not a type of First Order Logic (FOL) Sentence? | | |
| a) a. Atomic sentence | | |
| c) c. Quantified sentence | b) b. Complex sentences | |
| (16) A constructive approach in which no committee | d) d. Quality Sentence | |
| (16) A constructive approach in which no commitme o, is | ent is made unless it is necessary to do s | |
| a) a. Least commitment approach | b) b Most as a | |
| c) c. Nonlinear planning | b) b. Most commitment approach | |
| (17) A plan that describes how to take actions in leve city is | d) d. Opportunistic planning | |
| a) a. Problem solving | | |
| c) c. Non-hierarchical plan | b) b. Planning | |
| | d) d. Hierarchical plan | |
| (18) Uncertainty arises in the Wumpus world because a) a. Full & Global information | the agent's sensors give only | |
| c) c. Partial & local Information | b) b. Partial & Global Information | |
| o, o. 1 arctar as rocar information | d) d. Full & local information | |

(19) Partial order planning involves a) a. Searching over the space of possible plans LIBRARY c) c. Searching the whole problem at once Brainware University (20) Two literals are complementary if Barasat, Kolkata -700125 b) b. Searching over possible situations a) a. They are equal d) d. Searching the best c) c. They are identical but of opposite sign (21) Third component of a planning system is to b) b. They are identical and of equal sign a) a. Detect when a solution has been found d) d. They are unequal but of equal sign c) c. Detect whether solution exists or not (22) Which of the following is true related to 'Satisfiable' property? b) b. Detect when solution will be found a) a. A statement is satisfiable if there is some i d) d. Detect whether multiple solutions exist nterpretation for which it is false c) c. A statement is satisfiable if there is no inte b) b. A statement is satisfiable if there is some i rpretation for which it is true nterpretation for which it is true (23) Inference algorithm is complete only if d) d. A statement is satisfiable if there is no inte rpretation for which it is false a) a. It can derive any sentence c) c. It is truth preserving b) b. It can derive any sentence that is an entail ed version (24) Which search uses the problem specific knowledge beyond the definition of the proble d) d. It can derive any sentence that is an entail c) c. Breadth-first search b) b. Depth-first search (25) Default reasoning is another type of d) d. Uninformed search a) a. Monotonic reasoning c) c. Bitonic reasoning b) b. Analogical reasoning (26) Which of the following is true in Statistical reasoning? d) d. Closed world assumption. a) a. The representation is extended to allow so me kind of numeric measure of certainty to b b) b. The representation is extended to allow 'T e associated with each statement RUE or FALSE' to be associated with each s c) c. The representation is extended to allow so tatement me kind of numeric measure of certainty to b d) d. The representation is extended to allow 'T e associated common to all statements RUE or FALSE' to be associated common to (27) Treatment chosen by doctor for a patient for a disease is based on all statements a) a. Only current symptoms b) b. Current symptoms plus some knowledge f rom the textbooks c) c. current symptoms plus some knowledge fr d. All of these om the textbooks plus experience (28) ANNs are complex ------with many parameters. a) Linear Functions b) Nonlinear Functions c) Discrete Functions d) Exponential Functions (29) Defination of Generality is a) Ease with which the method can be adapted t b) The average time required to construct the ta rget knowledge structures from some specifi o different domains of applicatio ed initial structures d) A learning system to function with unreliabl c) A learning system to function with unreliabl e feedback and with a variety of training exa e feedback and with a variety of training exa

| Manager and the second | mples | |
|---|--|--|
| mples. | makes letter decision? | |
| mples. (30) Which modifies the performance element so that it makes tetter decision? (b) Changing element | | |
| a) Performance element | d) None of these | |
| c) Learning element (31) What test reach you destination of decision tree? | | |
| (31) What test reach you destribution of | -/ | |
| a) Single test | d) No test | |
| c) Sequence of test(32) How many things are concerned in the design of | a learning element? | |
| (32) How many things are concerned in | b) 2 | |
| a) 1 | d) 4 | |
| c) 3 (33) Which models is/are used in machine learning? | · 14-712 | |
| | b) Neural network | |
| a) Decision tree | d) All of these | |
| c) Propositional and FOL rule | | |
| (34) full form of ANN is | b) Artificial neuron network | |
| a) Artificial neural network | d) Artificial neural networking | |
| c) Ameno neural network | u) / | |
| (35) Automated vehicle is an example of | b) Unsupervised learning | |
| a) Supervised learning | d) Reinforcement learning | |
| c) Active learning | | |
| (36) ML is a field of Al consisting of learning algori | ithms that? | |
| a) Improve their performance | b) At executing some tass | |
| a) Over time with experience | d) All of the above | |
| (37) The model will be trained with data in one sing | le batch is known as ? | |
| a) Batch learning | b) Offline learning | |
| . n. d. 4 4 D | d) None of the above | |
| (20) In Model based learning methods, an iterative | process takes place on the ML models in called? | |
| at are built based on various model parameters. | b) optimizedparameters | |
| a) mini-batches | d) superparameters | |
| c) hyperparameters | | |
| (39) To find the minimum or the maximum of a fun | ction, we set the gradient to zero seems | |
| e: | b) 1 a | |
| a) The value of the gradient at extrema of a fun | Depends on the type of problem | |
| ction is always zero | d) None of the above | |
| c) Both A and B | , | |
| (40) Which of the following is an example of active | e learning: | |
| a) News recommender system | b) Dust cleaning machine | |
| c) Automated vehicle | d) None of these | |
| (41) Which of the following is not an application of | f learning? | |
| a) Data mining | b) WWW | |
| c) Speech recognition | d) None of these | |
| (42) Which of the following is also called as explo | ratory learning? | |
| a) Supervised learning | b) Active learning | |
| c) Unsupervised learning | d) All of these | |
| (43) Which of the following is not the promise of | | |
| (45) Willest of the following is not the profitise of | TOWN THOUSAND THE CONTROL OF THE CON | |

| avalain result | b) It can survive the failure of so | me nodes |
|---|--|---|
| a) It can explain result c) It has inherent parallelism | d) It can handle noise | |
| a) It tall that inherent parallelism c) It has inherent parallelism (44) The network that involves backward links to | from output to the input and hidden laye | ers is |
| (44) The network mans | b) Perceptron | Broke |
| (44) The network a) Self organizing maps c) Recurrent neural network | d) Multi layered perceptron | Brainware University Barasat, Keixata -700125 |
| c) Recurrent neutral new control of the control of | | Barasat, Keikata -700125 |
| c) Recurrent floated floated floated by (45) Decision Nodes are represented by | b) Squares | |
| a) Disks | d) Triangles | |
| c) Circles | 1 2 | |
| (46) End Nodes are represented by | b) Squares | |
| a) Disks | d) Triangles | |
| c) Circles | ontains the true function? | |
| c) Circles (47) What will happen if the hypothesis space co | b) Unrealizable | |
| a) Realizable | d) None of these | |
| c) Both Realizable & Unrealizable | to made unless it is necessary to | do s |
| c) Both Realizable & Unrealizable (48) A constructive approach in which no comm | itment is made unless it is not say, | |
| o is | b) Most commitment approach | |
| a) Least commitment approach | d) Opportunistic planning | |
| c) Nonlinear planning | | |
| (49) What kind of perception is used in printing? | b) Speech recognition | |
| a) Optical character recognition | d) None of these | |
| c) Perception | d) None of these | |
| (50) How many levels in parsing? | | |
| a) 3 | b) 2 | |
| c) 1 | d) 4 | |
| (51) What is the other name of each and every to | tal-order plan? | |
| a) Polarization | b) Linearization | |
| c) Solarization | d) None of these | |
| (52) What are not present in start actions? | | |
| a) Preconditions | b) Effect | |
| c) Finish | d) None of these | |
| (53) How many types of Artificial Neural Netwo | rks? | |
| | b) 3 | |
| a) 2 | d) 5 | |
| c) 4 (54) What is an auto-associative network? | | |
| (54) What is an auto-associative necessity of loops | b) a neural network that contains f | eedback eedback |
| a) a neural network that contains no loops | d) a single layer feed-forward neu | ral network w |
| c) a neural network that has only one loop | ith pre-processing | |
| (55) One word have different meaning, there need | d to select the meaning which makes the | e m |
| ost sense in context. This can be done by | | |
| | b) Word Sense Disambiguation | |
| a) Fuzzy Logic | d) All of these | |
| c) Shallow Semantic Analysi(56) Computational learning method analyses the | sample complexity and computational | co |
| (56) Computational learning method analyses the | | |
| mplexity of | b) Inductive learning | |
| a) Unsupervised Learning | d) Knowledge based learning | |
| c) Forced based learning | -/- | |

| (57) Two literals are similar if | |
|---|---|
| are equal | |
| c) They are identify | b) TI |
| c) They are identical but of opposite sign (58) If a robot can change its own trajectory in reply a) intelligent c) open loop | b) They are identical and of equal sign d) They are unequal but of equal sign |
| a) intelligent | to external conditions, it is considered t |
| | |
| (59) Which of the following is utilized to mapping s a) Text planning c) Text Realization | d) non-servo |
| a) Text planning | entence plan into |
| c) Text Realization | b) Sentence structure? |
| (60) Parts-of-Speech indicates | b) Sentence planning d) None of these |
| per meaning of the | |
| c) all part-of-speech for a specific word given a | b) part-of-speech for each word dynamically as per sentence structure |
| | d) All of these |