



## **BRAINWARE UNIVERSITY**

## Term End Examination 2023-2024 Programme – B.Tech.(RA)-2021 Course Name – Sensor and Actuator Devices for Robotics Course Code - PEC-ECR602A ( Semester VI )

Full Marks: 60	Time : 2:20 Have
[The figure in the margin indicates full mark	Time: 2:30 Hours s. Candidates are required to give their answers in their
own words	s as far as practicable.]
	Group-A
(Multiple Ch 1. Choose the correct alternative from the fo	hoice Type Question) 1 x 15=15  Allowing:
(i) Define the primary characteristic of the In	nternet of Things (IoT).
a) Centralized control     c) Offline operation     (ii) Duplicate which protocol is commonly use	b) Interconnectivity
a) HTTP c) MQTT (iii) Ask which IoT level involves integrating se objects?	b) SMTP
a) Level 0 c) Level 2 (iv) Cite which IoT domain focuses on optimizi	b) Level 1 d) Level 3 ing industrial processes and manufacturing?
a) Home IoT c) Energy IoT (v) Act, what is YANG in the context of IoT syst	b) City IoT
<ul> <li>a) A data modeling language</li> <li>c) A cloud computing technology</li> <li>(vi) Apply, what is SNMP commonly used for in</li> </ul>	b) A communication protocol
a) Device monitoring c) Cloud storage vii) Calculate, what role does NETOPEER play ir	b) Data encryption
<ul> <li>a) It acts as a network device agent</li> <li>c) It functions as a protocol translator</li> <li>iii) Read which of the following is a popular mi projects?</li> </ul>	b) It serves as a cloud server
a) Arduino c) Raspberry Pi	b) Zigbee

(ix)	Recite which programming language is commonly used for programming Raspberry Pi					
	in IoT projects? a) Python	b) C++				
	d) JavaScript					
(x)	<ul><li>c) Java</li><li>Extend which device is commonly used to conve to analog signals?</li></ul>					
	a) Digital-to-analog converter (DAC)					
	c) Relay	d) Transistor				
(xi)		de circuit for controls				
	a) Servo motor					
(xii)	c) Stepper motor Interpret, how do you control the direction of romicrocontroller?	d) Transistor notor requires an H-bridge circuit for control?  b) DC motor d) AC motor ontrol the direction of rotation of a DC motor using a  ge directly b) By using a servo motor d) By using an H-bridge circuit light sensor detect light intensity? b) By generating an electrical signal proportional to light intensity measuring the d) By converting light into sound waves stion of a cloud storage model? b) To provide unlimited storage space d) To host web applications f a communication API in IoT systems? loud storage b) To facilitate communication between IoT devices d) To regulate temperature in IoT				
	a) By changing the voltage directly					
	c) By using PWM signals					
(xiii)	Enumerate how does a light sensor detect light i					
	a) By measuring electrical resistance	proportional to light intensity				
	c) By emitting light and measuring the reflection	d) By converting light into sound waves				
(xiv)	Report the primary function of a cloud storage n	nodel?				
	a) To store data locally	•				
	c) To store data remotely	-				
(xv)	Research the purpose of a communication API in					
3	a) To provide access to cloud storage	5.	loT			
	c) To host web applications	d) To regulate temperature in IoT environments				
	Group	р-В				
	(Short Answer Ty		3 x 5=15			
2 Fn	umerate two IoT protocols and explain their sign	ificance in IoT communication	(3)			
	ccuss the advantages and limitations of using Pyt		(3)			
	strate the methods employed for speed control	of a DC motor in IoT systems.	(3)			
5. Discuss how cloud computing enhances scalability and flexibility in IoT deployments.						
6. Analyze the Internet of Things (IoT) and highlight its key characteristics.						
·	OR		2 2			
IIIu	strate sensors and actuators in the context of lo	T. Provide examples of each.	(3)			
	Group	n-C				
	(Long Answer Ty		E v 6-20			
	(Long / mower Ty)	oc Questions)	5 x 6=30			
7. De	efine and compare Software Defined Networks	SDN) and Network Function Virtualizati	on (5)			
3. Cc	FV) in the context of IoT deployments. How do empare and differentiate Arduino and Raspberry	( Pi in terms of bardware are attricted	/=\			
n cc	ogramming languages, and suitability for different	y rum terms of nardware specifications,	(5)			
e. Ex	plain how pulse width modulation (PWM) is use	ed for motor speed control in lot proise	tc /E\			
Pr	ovide examples of PWM implementation in con	trolling motor speed.				
lo. Co	impare and discriminate between different type	es of motion detection sensors used in I	oT (5)			
ар	plications, such as passive infrared (PIR) sensor	s, ultrasonic sensors, and microwave	(5)			

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- 11. Rewrite the benefits and challenges of using cloud computing for IoT deployments. Discuss (5) scalability, reliability, security, and cost considerations when choosing cloud offerings for IoT projects.
- 12. Categorize the architecture of an IoT system, detailing the roles of sensors, actuators, communication protocols, and cloud infrastructure. (5)

Contrast and compare different IoT communication protocols such as MQTT, CoAP, and HTTP in terms of their efficiency, scalability, and suitability for different applications. (5)