

- c) The birth death process. d) None of these.
- (17) For a process if v_i denotes the rate of transition from one state to another state, then a state is called instantaneous if
- a) $v_i = 0$ b) $v_i \rightarrow \infty$
 c) $v_i = -\infty$ d) none of the above
- (18) The birth and death process is a
- a) continuous time Markov chain b) discrete time Markov chain
 c) discrete state Markov chain d) none of the above
- (19) A continuous time Markov chain is said to be regular, if,
- a) it's with probability 1, the number of transitions in any finite length of time is finite. b) it's with probability 0, the number of transitions in any finite length of time is finite.
 c) it's with probability 1, the number of transitions in any finite length of time is infinite. d) none of the above

(20)

The number of recurrent classes in the transition matrix

$$\begin{pmatrix} 0.8 & 0 & 0 & 0 & 0.2 \\ 0 & 0.6 & 0 & 0.4 & 0 \\ 0.1 & 0.2 & 0 & 0.3 & 0.4 \\ 0 & 0.5 & 0 & 0.5 & 0 \\ 0.3 & 0 & 0 & 0 & 0.7 \end{pmatrix} \text{ are}$$

- a) 0 b) 1
 c) 2 d) 3
- (21) If the coefficients $\{\lambda_j\}$ and $\{\mu_j\}$ are called the birth and death rates respectively, then a process is said to be pure birth process if
- a) $\mu_j = 0$ b) $\mu_j = 1$
 c) $\lambda_j = 0$ d) $\lambda_j = 1$
- (22) In the long run, the state probabilities become 0 & 1
- a) In no case b) In some cases
 c) In all cases d) Cannot say
- (23) If a matrix of transition probability is of order $n \times n$, then the number of equilibrium equations
- a) n b) n-1
 c) n+1 d) n+2
- (24) In a matrix of transition probability, the element a_{ij} , where $i=j$ is a
- a) Gain b) Loss
 c) Retention d) None of the above
- (25) In a matrix of transition probability, the probability values should add up to one in each

- c) Equal to
- d) Does not depend on
- (46) Stochastic processes are
- a) Strict sense stationary process
- b) Wide sense stationary process
- c) All of the mentioned
- d) None of the mentioned
- (47) Gaussian process is a
- a) Wide sense stationary process
- b) Strict sense stationary process
- c) If Gaussian process is a wide sense stationary process then it will also be strict sense stationary process.
- d) None of the mentioned
- (48) One of the condition for a counting process $\{N(t), t \geq 0\}$, is said to be Poisson process if-
- a) $N(0)=0$
- b) $N(0)=1$
- c) $N(1)=0$
- d) $N(1)=1$
- (49) Cov (X, Y) {covariance of (X, Y) is}
- a) $E(XY)$
- b) $E(XY) - E(X)$
- c) $E(XY) - E(X)E(Y)$
- d) $E(XY) + E(X)E(Y)$
- (50) If $R_{XY} = 0$ then X and Y are
- a) independent
- b) orthogonal
- c) independent & orthogonal
- d) Statistically independent
- (51) The collection of all the sample functions is referred to as
- a) Ensemble
- b) Assemble
- c) Average
- d) Set
- (52) The random process X(t) and Y(t) are said to be independent, if $f_{XY}(x_1, y_1 : t_1, t_1)$ is =
- a) $f_X(x_1 : t_1)$
- b) $f_Y(y_1 : t_2)$
- c) $f_X(x_1 : t_1) f_Y(y_1 : t_2)$
- d) 0
- (53) A stationary continuous process X(t) with auto-correlation function $R_{xx}(\tau)$ is called autocorrelation-ergodic or ergodic in the autocorrelation if, and only if, for all τ
- a) $\frac{1}{2T} \int_{-T}^T X(t)X(t+\tau)dt = R_{xx}(\tau)$
- b) $\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T X(t)X(t+\tau)dt = R_{xx}(\tau)$
- c) $\frac{1}{2T} \int_{-\infty}^{\infty} X(t)X(t+\tau)dt = R_{xx}(\tau)$
- d) $\int_{-T}^T X(t)dt = 0$
- (54) Two processes X(t) and Y(t) are statistically independent if
- a) $F_{X,Y}(x_1, x_2, \dots, x_N, y_1, y_2, \dots, y_M) = F_X(x_1, x_2, \dots, x_N) F_Y(y_1, y_2, \dots, y_M)$
- b) $f_{X,Y}(x_1, x_2, \dots, x_N, y_1, y_2, \dots, y_M) = f_X(x_1, x_2, \dots, x_N) f_Y(y_1, y_2, \dots, y_M)$
- c)
- d)

$$F_{x,y}(x_1, \dots, x_N, y_1, \dots, y_M, t_1, \dots, t_N, t_1, \dots, t_M) = f_x(x_1, \dots, x_N, t_1, \dots, t_N) f_y(y_1, \dots, y_M, t_1, \dots, t_M)$$

(55)

A process stationary to all orders $N = 1, 2, \dots$ &. For $X_i = X(t_i)$ where $i = 1, 2, \dots, N$ is called

- a) Strict-sense stationary
- b) wide-sense stationary
- c) Strictly stationary
- d) independent

(56) Consider a random process $X(t)$ defined as $X(t) = A \cos wt + B \sin wt$, where w is a Constant and A and B are random variables which of the following it's a condition for its stationary.

- a) $E(A) = 0, E(B) = 0$
- b) $E(AB) \neq 0$
- c) $E(A) \neq 0; E(B) \neq 0$
- d) A and B should be independent

(57)

$X(t)$ is a wide source stationary process with $E[X(t)] = 2$ and $R_{XX}(\tau) = 2$ and

$$R_{XX}(\tau) = 2 + e^{-0.1|\tau|}. \text{ Find the mean and variance of } \int_0^1 X(t) dt$$

- a) 2, 20 $[10e^{-0.1} - 9]$
- b) 1, 10 $[10e^{-0.1} + 9]$
- c) 0, 5 $[20e^{-0.1} - 9]$
- d) 0, 10 $[10e^{-0.1} + 9]$

(58)

Let $X(t)$ and $Y(t)$ be two random processes with respective auto correlation functions $R_{xx}(\tau)$ and $R_{yy}(\tau)$. Then $|R_{xy}(\tau)| =$

- a) $= \sqrt{R_{xx}(0)R_{yy}(0)}$
- b) $\geq \sqrt{R_{xx}(0)R_{yy}(0)}$
- c) $\leq \sqrt{R_{xx}(0)R_{yy}(0)}$
- d) $> \sqrt{R_{xx}(0)R_{yy}(0)}$

(59)

$$R_{XX}(\tau) = ?$$

- a) $E[X^2(t)]$
- b) $\int_{-\infty}^{\infty} X(t) dt$
- c) $\int_{-\infty}^{\infty} X^2(t) dt$
- d) $E[X(t)X(t+\tau)]$

(60)

If X_1, X_2, \dots are independent and identically distributed with mean m , then

$$P\left\{\lim_{n \rightarrow \infty} (X_1 + X_2 + \dots + X_n) / n = \mu\right\} = ?$$

- a) 0
- b) 1
- c) 2
- d) None of these